

EgoCap: Egocentric Marker-less Motion Capture with Two Fisheye Cameras

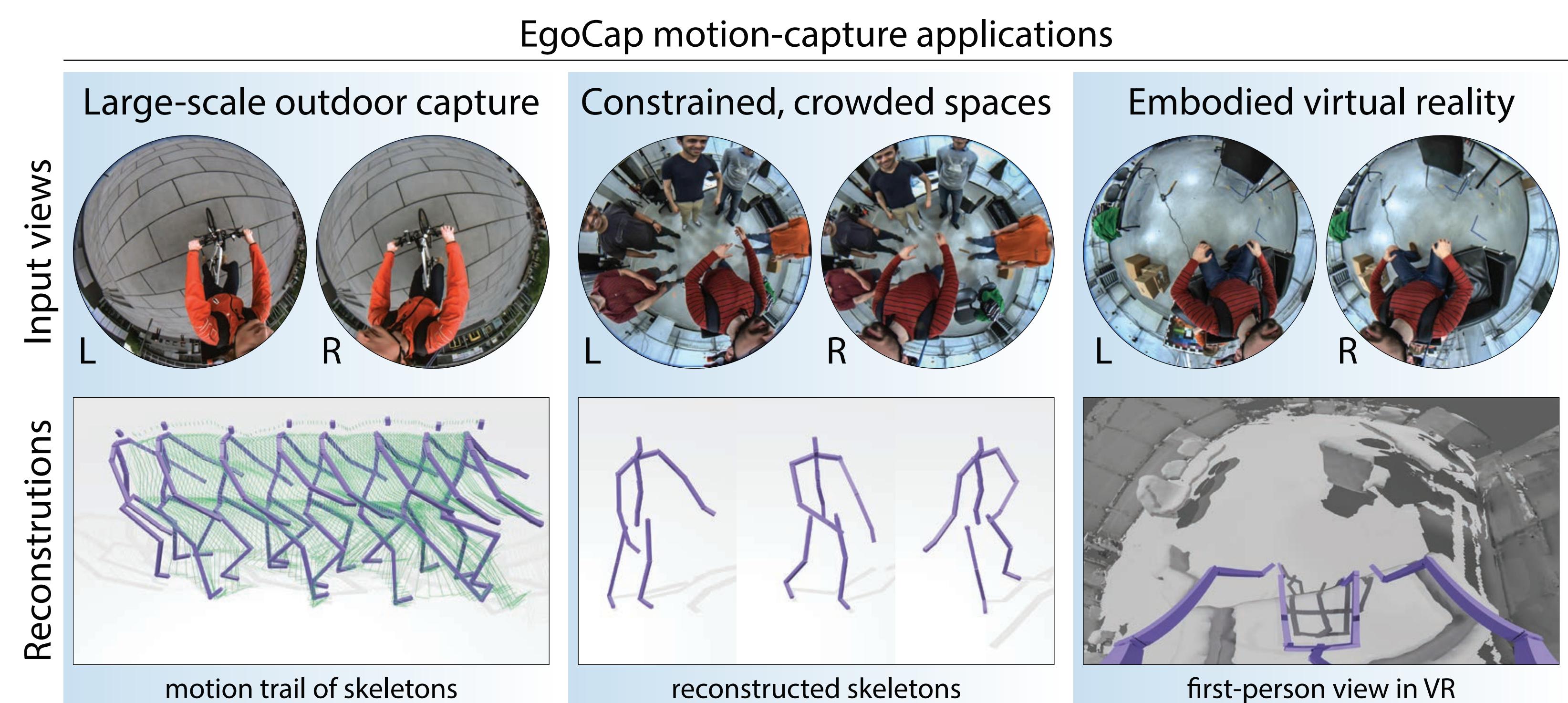
SIGGRAPH Asia 2016
Database available

Helge Rhodin¹ Christian Richardt^{1,2,3} Dan Casas¹ Eldar Insafutdinov¹ Mohammad Shafiei¹
Hans-Peter Seidel¹ Bernt Schiele¹ Christian Theobalt¹

¹Max Planck Institute for Informatics ²Intel Visual Computing Institute ³University of Bath

Contributions

- Egocentric inside-in camera rig
- Motion capture algorithm (generative + discriminative)
- Automatic database (annotation & augmentation)

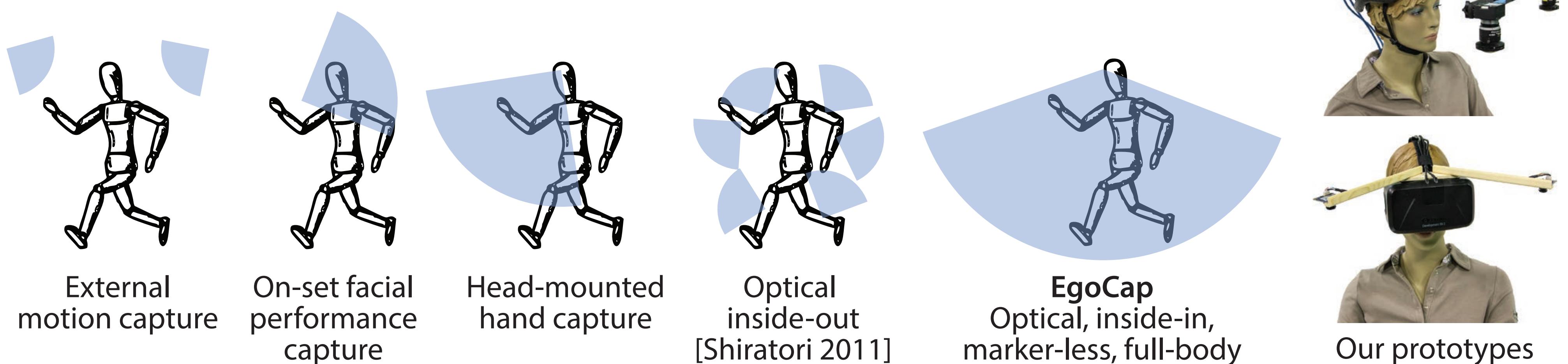


Advantages

- Free roaming
- Succeeds in crowded scenes
- Easy to use, little intrusion

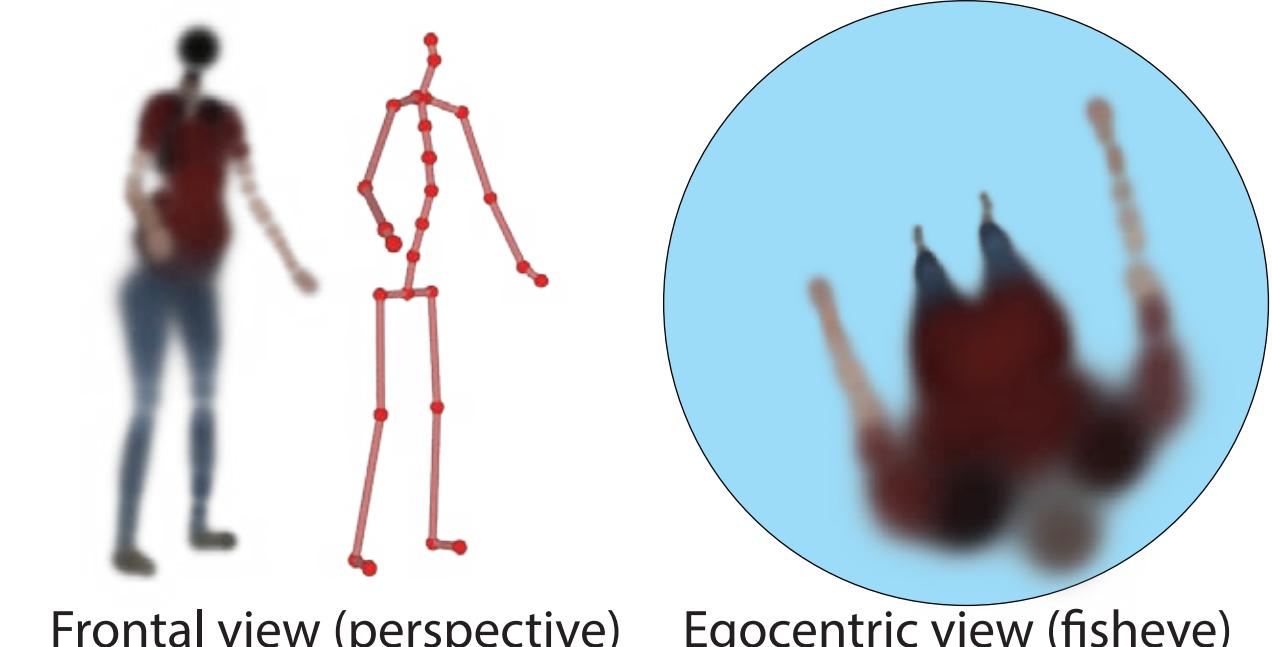
Capture approaches

- Inside-in, outside-in, inside-out
- Optical, accelerometer, exoskeleton
- Head-mounted, external, suit-based
- Full-body pose, hands, faces, surface
- Marker-less, active or passive markers

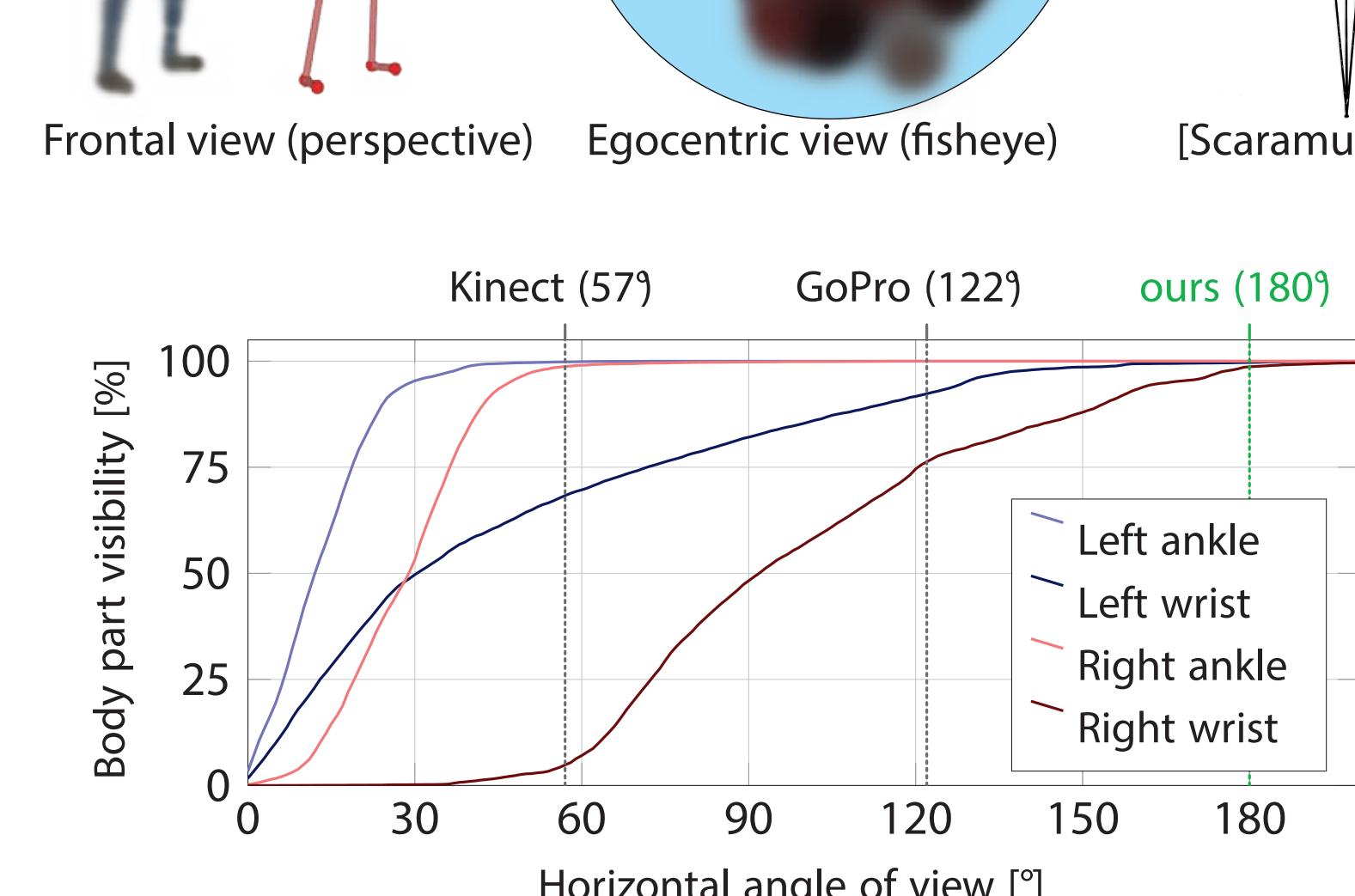
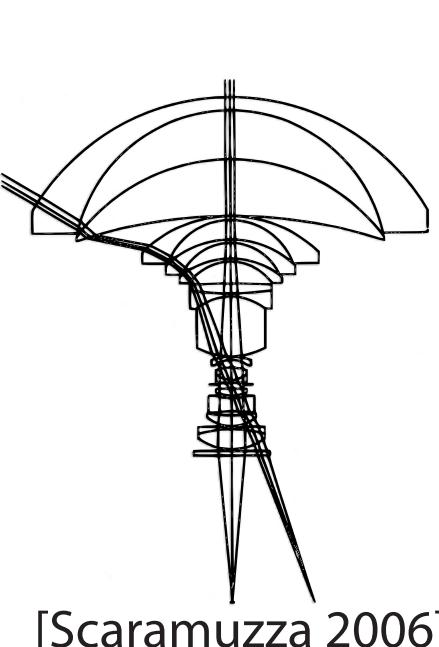


Generative model

Volumetric model + skeleton

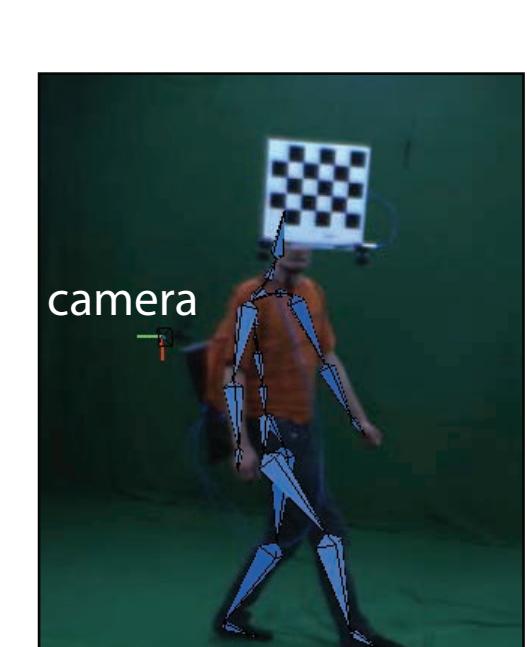


Lens model

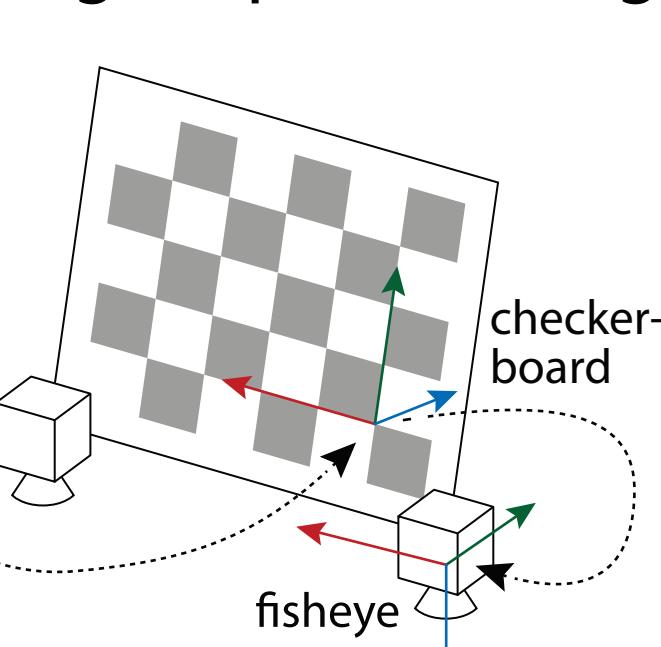


Database creation

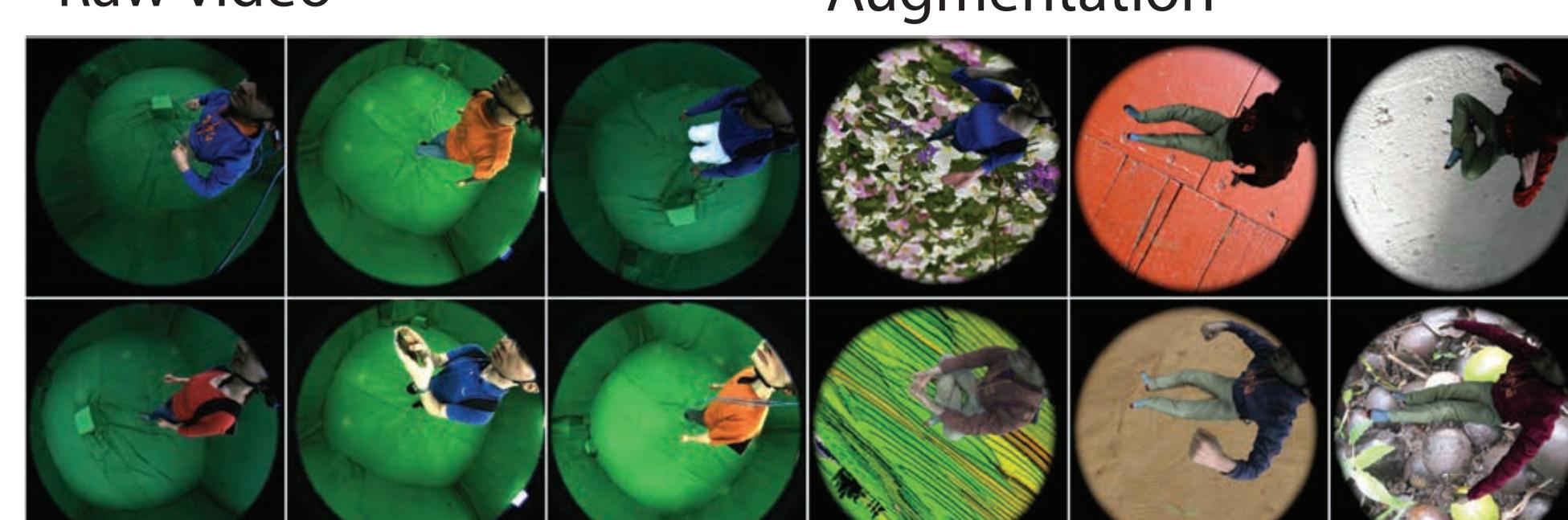
Multi-view motion capture system



EgoCap camera rig

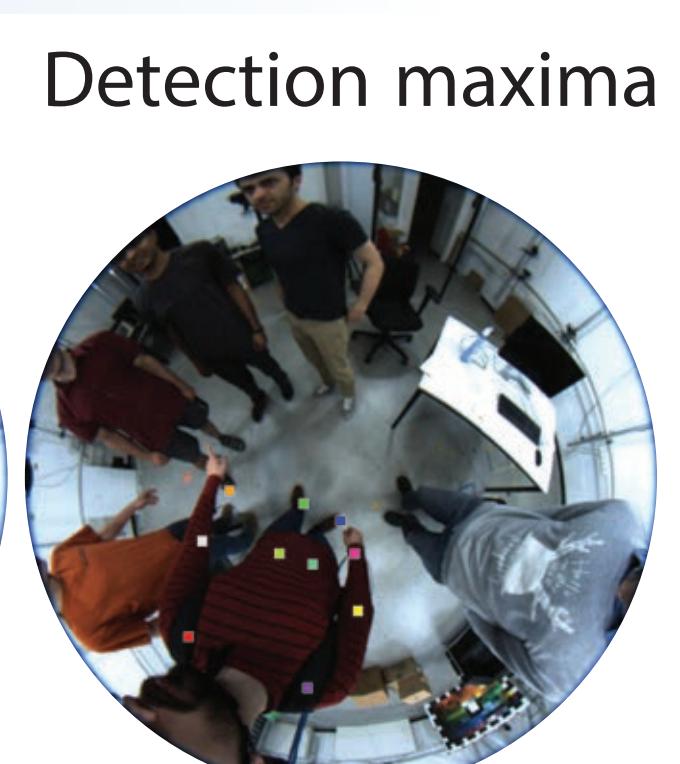
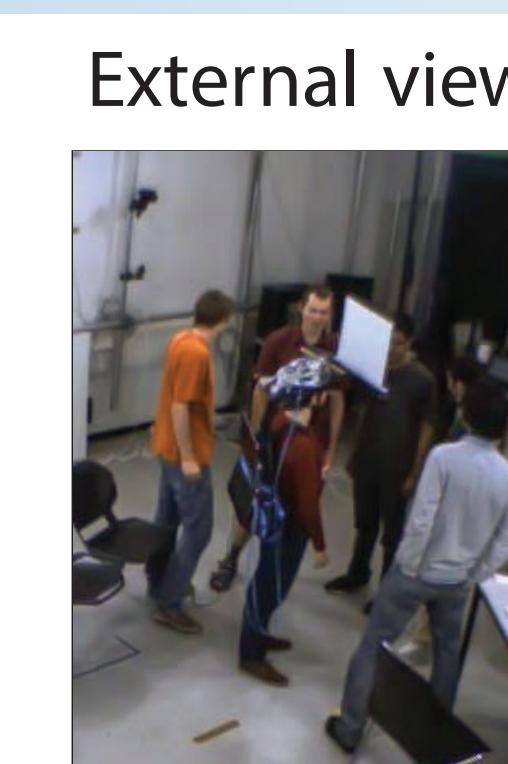


Raw video

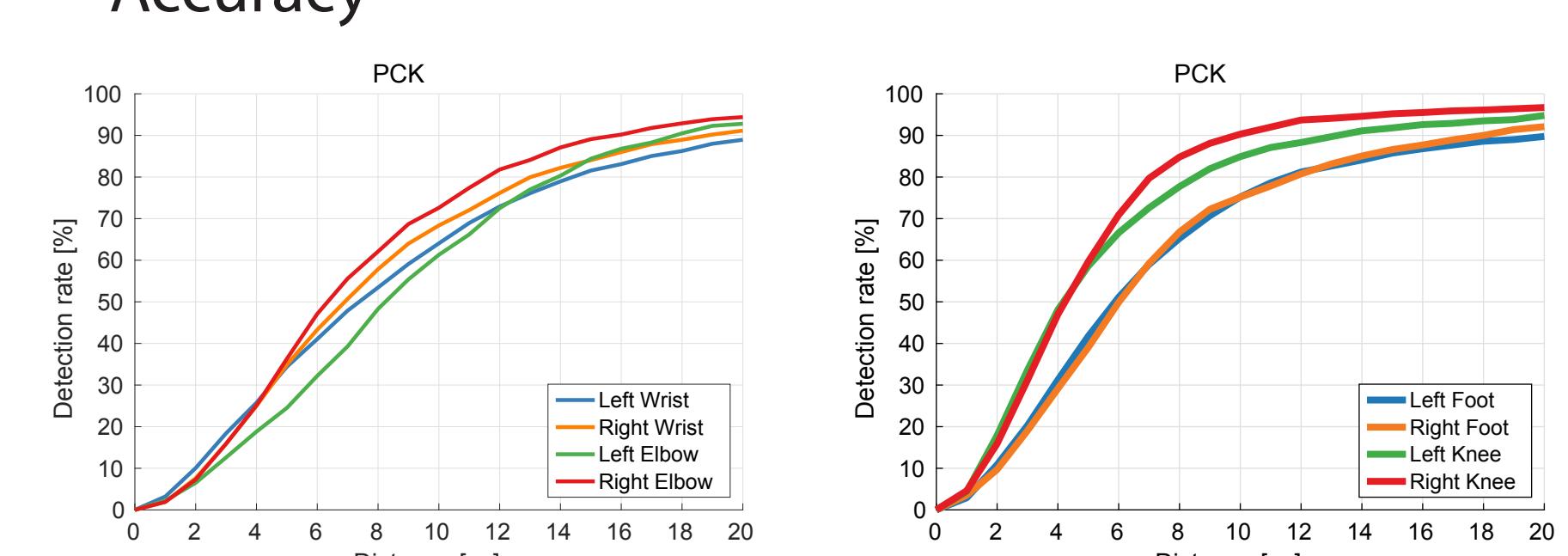


Augmentation

Discriminative model

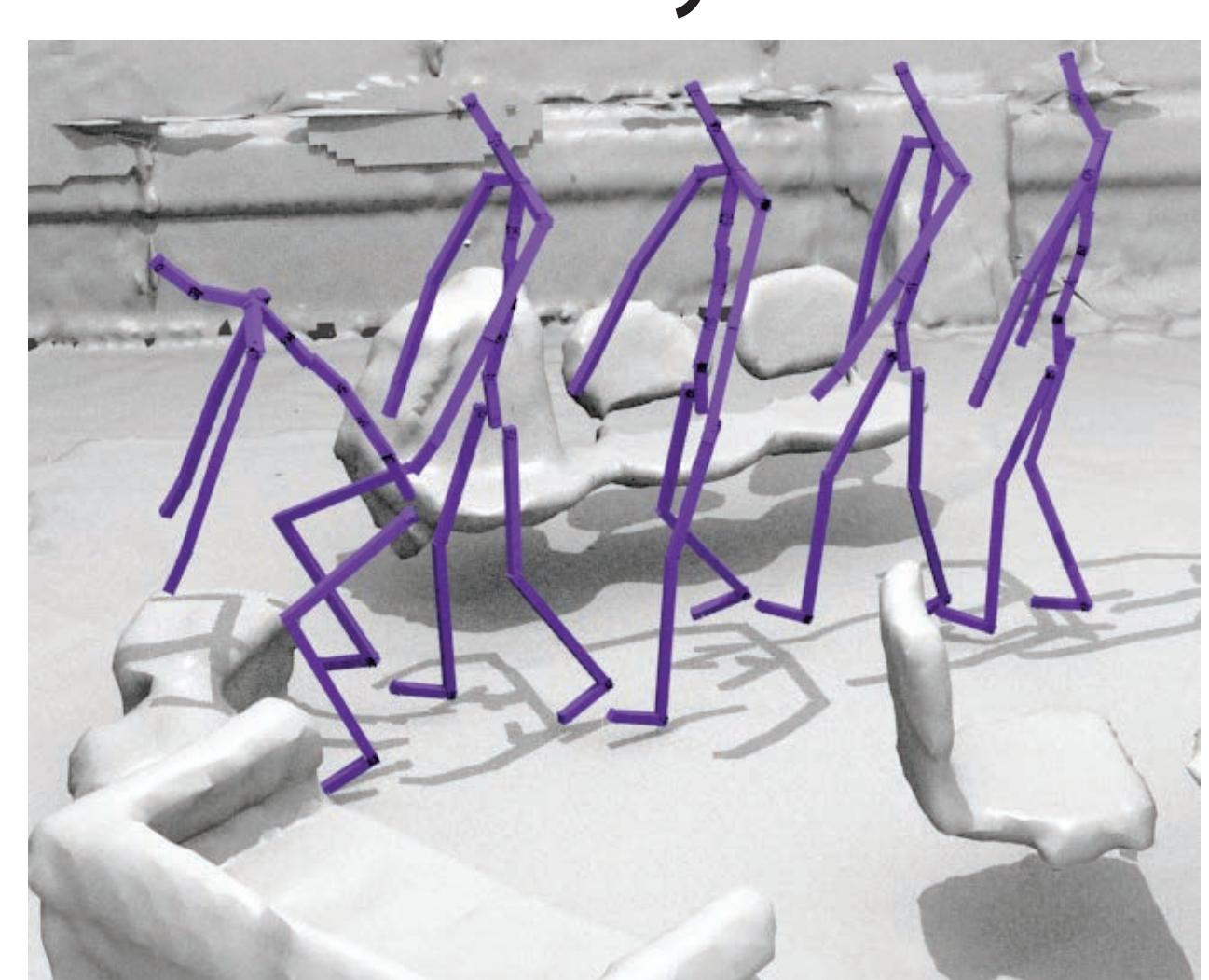


Accuracy

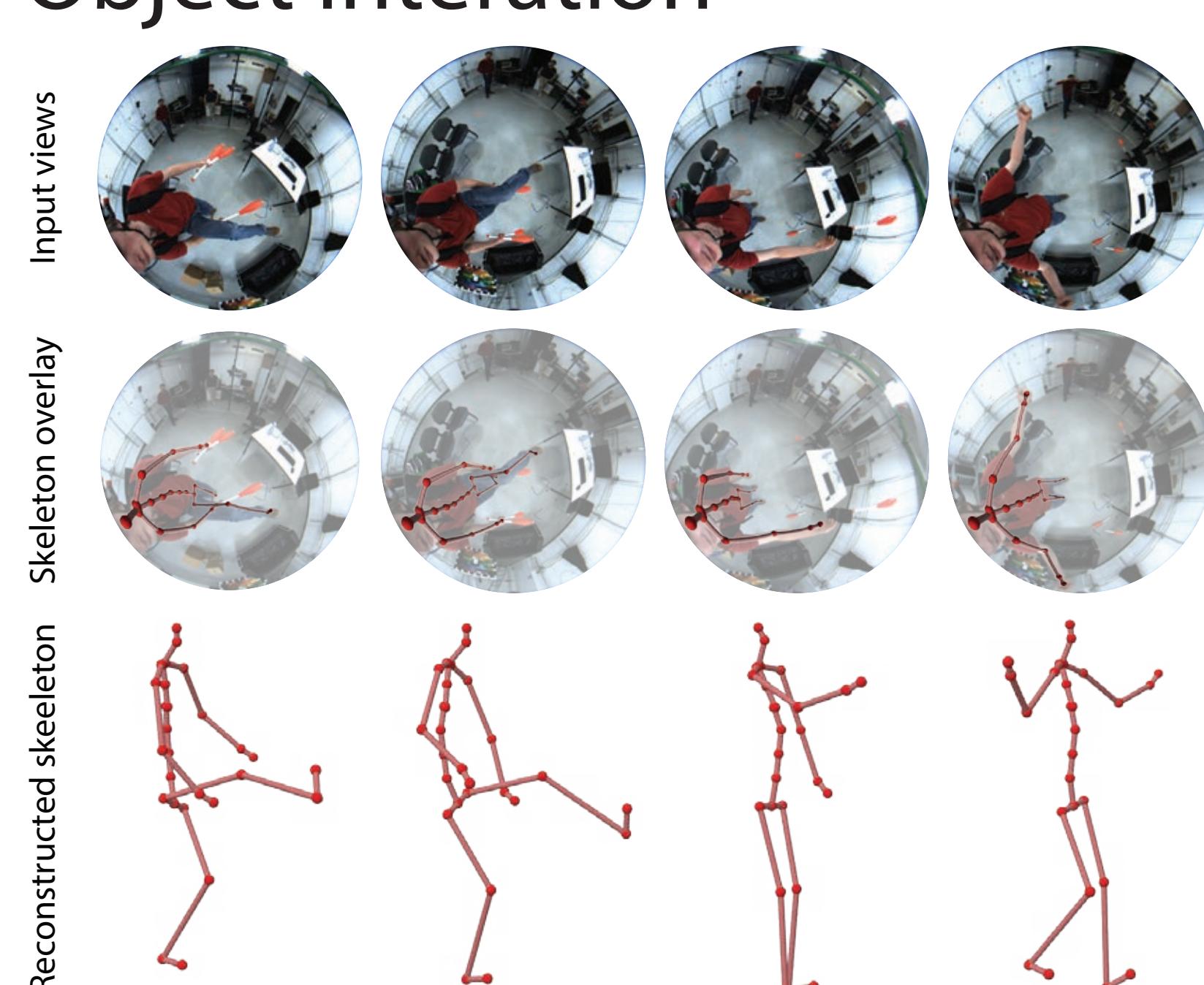


Results

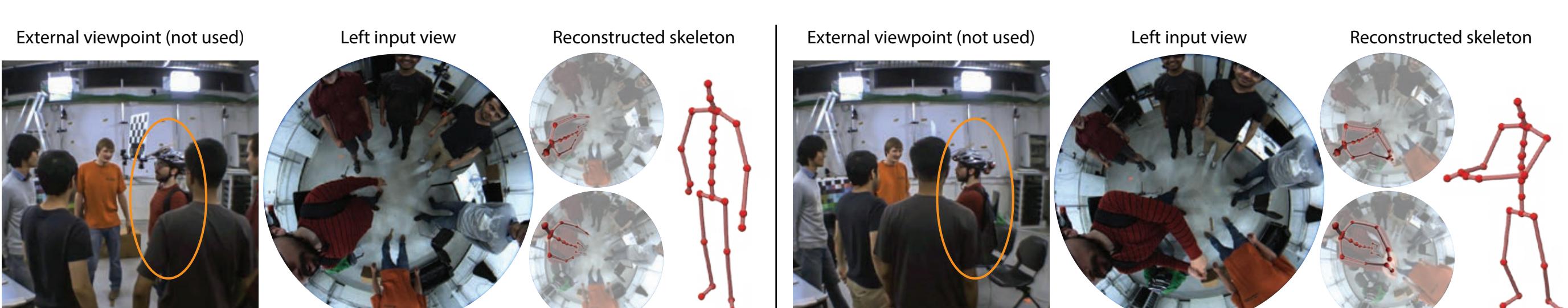
Virtual reality



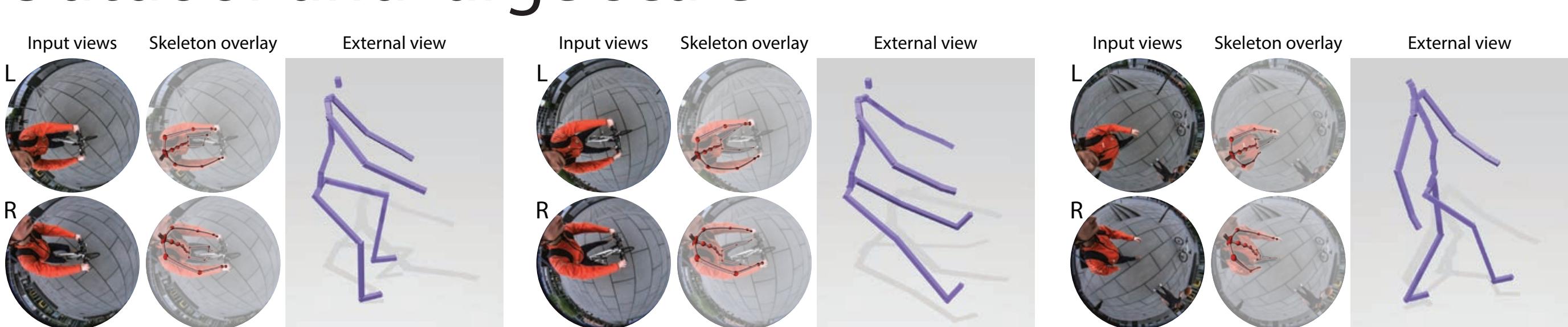
Object interaction



Crowded and confined scenes



Outdoor and large scale



Funding: ERC starting grant CapReal (335545)

Project page: gvv.mpi-inf.mpg.de/projects/EgoCap

Database: gvvperfcapeva.mpi-inf.mpg.de